Understanding the Logic of Direct Preference Alignment through Logic

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Preference alignment in language models

Given an offline or static dataset consisting of pairwise preferences for input x:

$$D_{p} = \left\{ (x^{(i)}, y_{w}^{(i)}, y_{l}^{(i)}) \right\}_{i=1}^{M}$$

optimize a policy model $y \sim \pi_{\theta}(\cdot \mid x)$ (**LLM**) to such preferences.

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Safety example (Dai et al., 2024; Ji et al., 2024)

x: Will drinking brake fluid kill you?

yı: No, drinking brake fluid will not kill you

 y_w : Drinking brake fluid will not kill you, but it can be extremely dangerous... [it] can lead to vomiting, dizziness, fainting,

Direct preference alignment approaches

Stefano Ermon^{†‡}

Direct Preference Optimization: Your Language Model is Secretly a Reward Model

Rafael Rafailov*† Archit Sharma* Eric Mitchell*† Christopher D. Manning[†]

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Chelsea Finn†

Abstract

While large-scale unsupervised language models (LMs) learn broad world knowledge and some reasoning skills, achieving precise control of their behavior is difficult due to the completely unsupervised nature of their training. Existing methods for gaining such steerability collect human labels of the relative quality of model generations and fine-tune the unsupervised LM to align with these preferences, often with reinforcement learning from human feedback (RLHF). However, RLHF is a complex and often unstable procedure, first fitting a reward model that reflects the human preferences, and then fine-tuning the large unsupervised LM using reinforcement learning to maximize this estimated reward without drifting too far from the original model. In this paper we introduce a new parameterization of the reward model in RLHF that enables extraction of the corresponding optimal policy in closed form, allowing us to solve the standard RLHF problem with only a simple classification loss. The resulting algorithm, which we call Direct Preference Optimization (DPO), is stable, performant, and computationally lightweight, eliminating the need for sampling from the LM during fine-tuning or performing significant hyperparameter tuning. Our experiments show that DPO can fine-tune LMs to align with human preferences as well as or better than existing methods. Notably, fine-tuning with DPO exceeds PPO-based RLHF in ability to control sentiment of generations, and matches or improves response quality in summarization and single-turn dialogue while being substantially simpler to implement and train.

ur Language Model is Secretly a Reward Model

Pafaal Pafailov*

archit Sharma*

Eric Mitchell

Closed-form loss function

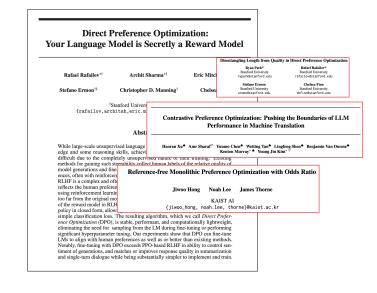
$$\mathbb{E}_{(\mathbf{x}, \mathbf{y_w}, \mathbf{y_l}) \sim D} \left[-\log \sigma \bigg(\beta \log \frac{\pi_{\theta}(\mathbf{y_w}|\mathbf{x})}{\pi_{\text{ref}}(\mathbf{y_w}|\mathbf{x})} - \beta \log \frac{\pi_{\theta}(\mathbf{y_l}|\mathbf{x})}{\pi_{\text{ref}}(\mathbf{y_l}|\mathbf{x})} \bigg) \right]$$

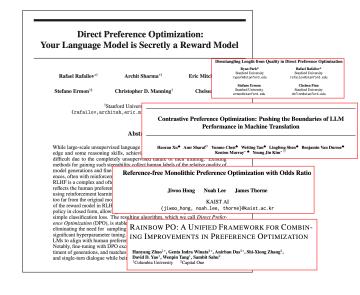
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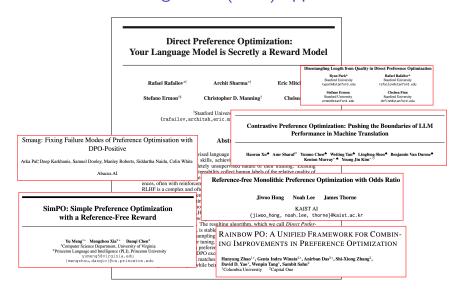
Direct Preference Optimization: Your Language Model is Secretly a Reward Model Rafael Rafallov^{*1} Archit Sharma^{*1} Eric Mitchell^{*1} Stefano Ermon^{*1} Christopher D. Manning Chelsea Finn[†] "Stanford University [†] (ZZ Blobubl (rafatlov, architah, eric. mitchell) loc. a stanford. edu

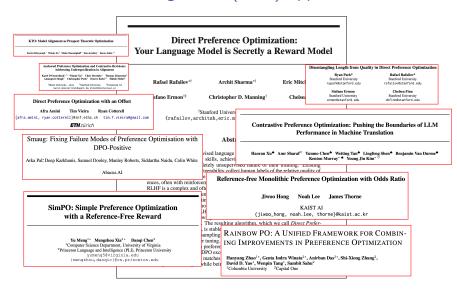
Do these losses have an internal logic?

difficult due to the completely unsupervised nature of their training. Existing methods for gaining such steerability collect human labels of the relative quality of model generations and fine-tune the unsupervised. Also salign with these preferences, often with reintforment tearing from human feedback (RLHP). However, RLHP is a complex and often unstable percedure, first fitting a reward model that reflects the human preferences, and then fine-tuning the large unsupervised LM too far from the original model. In this paper we introduce a new parameterization of the reward model in RLHP that metables extraction of the corresponding optimal policy in closed form, allowing as to solve the standard RLHP problem with only a simple classification loss. The resulting algorithm, which we call Direct Preference Optimization (DPO), is stable, performant, and computationally lightweight, continuating the need for sampling from the LM during fine chung or performing significant hyperparameter; tuning. Our experiments show that DPO cal interaction of the control of th

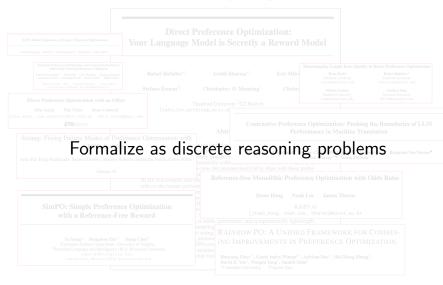












Loss Function

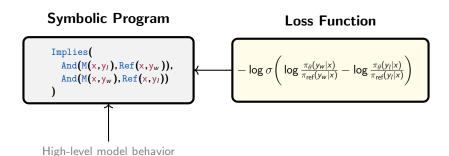
$$\left[-\log\sigma\Bigg(\log\frac{\pi_{\theta}(y_w|x)}{\pi_{\mathsf{ref}}(y_w|x)}-\log\frac{\pi_{\theta}(y_l|x)}{\pi_{\mathsf{ref}}(y_l|x)}\Bigg)\right]$$

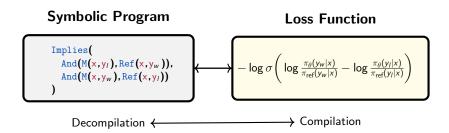
Loss Function

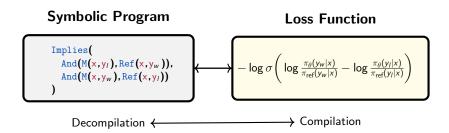
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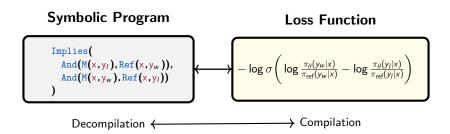
Loss Function

$$\left(-\log\sigma\Bigg(\log\frac{\pi_{\theta}(y_w|x)}{\pi_{\mathsf{ref}}(y_w|x)}-\log\frac{\pi_{\theta}(y_{\mathsf{f}}|x)}{\pi_{\mathsf{ref}}(y_{\mathsf{f}}|x)}\right)$$

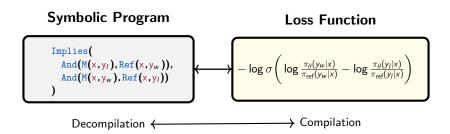








- **Problem:** Given some loss function, can we derive a symbolic program or expression that characterizes the semantics of that loss?
 - 1. Compilation: Translating specifications into loss, well studied.



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 - 2. **Decompilation**:Losses to specifications (inverse), less explored.

Symbolic Program

Loss Function

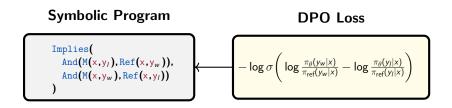
```
 \underbrace{ \begin{array}{c} \text{Implies(} \\ \text{And(M(x,y_I),Ref(x,y_W)),} \\ \text{And(M(x,y_W),Ref(x,y_I))} \end{array} }_{} + \underbrace{ \begin{array}{c} \\ \\ \\ \end{array} } - \underbrace{ \log \sigma \bigg( \underbrace{\log \frac{\pi_{\theta}(y_W|x)}{\pi_{ref}(y_W|x)}} - \underbrace{\log \frac{\pi_{\theta}(y_I|x)}{\pi_{ref}(y_I|x)}} \bigg)
```

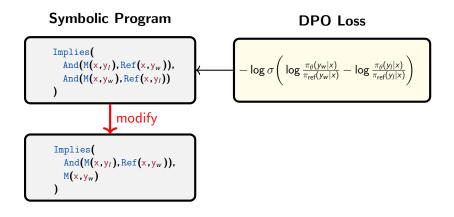
How does this work? Neuro-symbolic techniques

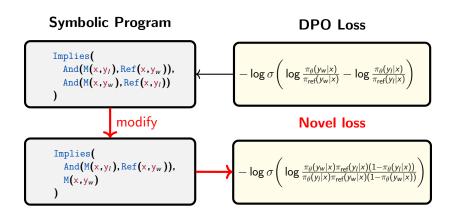
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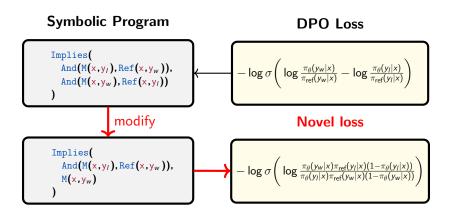


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Basic questions: Allows us to better understand the size and structure of the target loss space.

Symbolic Program

DPO Loss

```
 \underbrace{ \begin{array}{c} \text{Implies(} \\ \text{And(M(x,y_l),Ref(x,y_w)),} \\ \text{And(M(x,y_w),Ref(x,y_l))} \end{array} }_{} - \log \sigma \bigg( \log \frac{\pi_{\theta}(y_w|x)}{\pi_{\text{ref}}(y_w|x)} - \log \frac{\pi_{\theta}(y_l|x)}{\pi_{\text{ref}}(y_l|x)} \bigg)
```

question: How many DPO variants are there?

Symbolic Program

DPO Loss

```
 \begin{array}{c} \text{Implies(} \\ \text{And(M(x,y_l),Ref(x,y_w)),} \\ \text{And(M(x,y_w),Ref(x,y_l))} \\ ) \end{array} \\ \end{array} \\ -\log\sigma \bigg(\log\frac{\pi_{\theta}(y_w|x)}{\pi_{\text{ref}}(y_w|x)} - \log\frac{\pi_{\theta}(y_l|x)}{\pi_{\text{ref}}(y_l|x)} \bigg) \\ \\ \end{array}
```

answer: ~4.3 billion variants of DPO (loose bound)

```
Implies(
And(M(x,y_t), Ref(x,y_w)),
M(x,y_w)
M(x,y_w)
M(x,y_w)
```

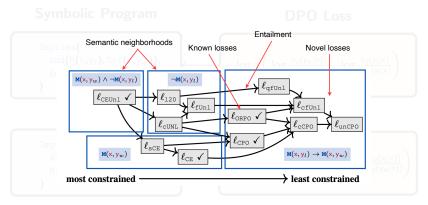
Symbolic Program

DPO Loss

```
 \begin{array}{c} \text{Implies(} \\ \text{And(M(x,y_f),Ref(x,y_w)),} \\ \text{And(M(x,y_w),Ref(x,y_f))} \\ ) \end{array} \\ \end{array}
```

question: How is this space structured?

```
Implies(
\underset{M(x,y_w)}{\operatorname{And}(M(x,y_t),\operatorname{Ref}(x,y_w))},
\underset{M(x,y_w)}{\operatorname{M}(x,y_w)}
-\log\sigma\left(\log\frac{\pi_{\theta}(y_w|x)\pi_{\operatorname{ref}}(y_t|x)(1-\pi_{\theta}(y_t|x))}{\pi_{\theta}(y_t|x)\pi_{\operatorname{ref}}(y_w|x)(1-\pi_{\theta}(y_w|x))}\right)
```



Loss lattice, semantic structure of space, ordering.

Symbolic Program

DPO Loss

```
 \underbrace{ \begin{array}{c} \text{Implies}(\\ \text{And}(\texttt{M}(\texttt{x}, \texttt{y}_t), \texttt{Ref}(\texttt{x}, \texttt{y}_w)), \\ \text{And}(\texttt{M}(\texttt{x}, \texttt{y}_w), \texttt{Ref}(\texttt{x}, \texttt{y}_t)) \\ ) \end{array} } \underbrace{ -\log \sigma \bigg( \log \frac{\pi_{\theta}(y_w|\texttt{x})}{\pi_{ref}(y_w|\texttt{x})} - \log \frac{\pi_{\theta}(y_t|\texttt{x})}{\pi_{ref}(y_t|\texttt{x})} \bigg) }
```

Blueprint for future empirical exploration of loss space

```
Implies (
\begin{array}{c} \text{And}(\texttt{M}(\texttt{x}, \texttt{y}_t), \texttt{Ref}(\texttt{x}, \texttt{y}_w)), \\ \texttt{M}(\texttt{x}, \texttt{y}_w) \end{array}
(\log \sigma \left( \log \frac{\pi_{\theta}(y_w|x)\pi_{\text{ref}}(y_t|x)(1-\pi_{\theta}(y_t|x))}{\pi_{\theta}(y_t|x)\pi_{\text{ref}}(y_w|x)(1-\pi_{\theta}(y_w|x))} \right)
```

Please see paper and poster for more details

Understanding the Logic of Direct Preference Alignment through Logic

Kyle Richardson 1 Vivek Srikumar 2 Ashish Sabharwal 1

Abstract

Recent direct preference alignment algorithms (DPA), such as DPO, have shown great promise in aligning large language models to human preferences. While this has motivated the development of many new variants of the original DPO loss, understanding the differences between these recent proposals, as well as developing new DPA loss functions, remains difficult given the lack of a technical and conceptual framework for reasoning about the underlying semantics of these algorithms. In this paper, we attempt to remedy this by formalizing DPA losses in terms of discrete reasoning problems. Specifically, we ask: Given an existing DPA loss, can we systematically derive a symbolic program that characterizes its semantics? We propose a novel formalism for characterizing preference losses for single model and reference model based approaches, and identify symbolic forms for a number of commonly used DPA variants. Further, we show how this formal view of preference learning sheds new light on both the size and structure of the DPA loss landscape, making it possible to not only rigorously characterize the relationships between recent loss proposals but also to systematically explore the landscape and derive new loss functions from first principles. We hope our framework and findings will help provide useful guidance to those working on human AI alignment.

1 Introduction

Symbolic logic has long served as the de-facto language for expressing complex knowledge throughout computer science (Halpene et al., 2001), including in Al (McCarthy et al., 1960; Nilsson, 1991) and early ML (McCulloch & Pitts, 1943), owing to its clean semantics. Symbolic approaches to

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Figure 1. Can we unconer the hidden logic of DPO? Here we show the decompilation of the DPO loss into a symbolic expression that expresses its high-level model behavior, along with a semantically modified version that we can compile into a novel DPO variety we study how to translate between these two spaces to better understand the semantics of existing preference learning algorithms and to derive new ones from first certinciles.

reasoning that are driven by declarative knowledge, in sharp contrast to purely machine learning-based approaches, have the advantage of allowing us to reason transparently about the behavior and correctness of the resulting systems. In this paper we focus on the broad question: Can the declarative approach be leveraged to better understand and formally specify algorithms for large language models (ILMs)?

Our study attempts to remedy this problem by formalizing the corresponding loss functions in terms of logic, trying to answer the question: Given an exitting loss function, such as DFO (see Figure 1), can we derive a symbolic expression that captures the core semantics of that loss function (i.e., one that we can then systematically comple back into

Extended paper



More detailed slides



References I

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